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1 **Insights into a membrane contactor based demonstration unit for CO₂ capture**

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7 **Abstract**

8 A continuously operated CO₂ capture unit, based on absorption in a membrane contactor and low-
9 temperature vacuum desorption, is demonstrated. The major advantage of membrane contactors is their
10 high specific interfacial area per unit volume. The unit is designed to be modular to allow different absorption
11 membrane modules and stripping units to be tested, with the aim of capturing CO₂ from simulated flue
12 gases at concentrations down to the ambient concentration. In addition, desorption can be performed under
13 vacuum to improve the desorption efficiency. The experimental unit incorporates comprehensive
14 measurements and a high level of automation, with heat integration and continuous measurement of
15 electricity consumption providing real-time estimates of the energy consumed in the capture process.

16 In preliminary tests, the results of which are described herein, a 3M Liqui-Cel™ polypropylene hollow-fiber
17 membrane module and a glass vacuum chamber were used for absorption and desorption, respectively,
18 along with a potassium glycinate amino acid salt absorbent solution. This solution has high surface tension
19 and is fully compatible with the polypropylene membrane unit used. In preliminary tests, the highest
20 observed CO₂ flux was 0.82 mol m⁻² h⁻¹, with a CO₂ product purity of above 80%. The calculated overall
21 mass transfer coefficient was comparable to reference systems. The performance of the unit in its current
22 setup was found to be limited by the desorption efficiency. Due to the low desorption rates, the measured
23 specific energy consumption was exceedingly high, at 4.6 MJ/mol CO₂ (29.0 MWh/t) and 0.8 MJ/mol CO₂
24 (5.0 MWh/t) of heat and electricity, respectively. Higher desorption temperatures and lower vacuum
25 pressures enhanced the desorption efficiency and reduced the specific energy consumption. The energy
26 efficiency could be improved via several methods in the future, e.g., by applying ultrasound radiation or by
27 replacing the current vacuum chamber stripping unit with a membrane module or some other type of
28 desorption unit.

29 **Keywords**

30 CO₂ capture, membrane contactor, vacuum, stripping, desorption, amino acid salt, potassium glycinate

31 **Declarations of interest:** none

32

33 1. Introduction

34 The development and implementation of carbon capture technologies is vital to mitigate the growing global
35 CO₂ emissions, which have been linked to detrimental climatic effects, most notably global warming [1].
36 Carbon capture refers to the separation of carbon dioxide (CO₂) from point emission sources, or potentially
37 directly from the atmosphere [2]. In the carbon capture and storage (CCS) approach, the captured CO₂ is
38 stored underground in geological formations like aquifers or depleted oil or gas fields [3]. Alternatively,
39 carbon capture and utilization (CCU) aims to convert the captured CO₂ into valuable products, such as fuels
40 or chemicals [4].

41 The most established technology for the separation of CO₂ from flue gases or process streams involves
42 the absorption of CO₂ into basic solutions such as aqueous amines, most commonly monoethanolamine
43 (MEA) [5, 6]. In the amine absorption process, CO₂ is chemically absorbed into the solution and then
44 released by heating the CO₂-loaded solution [3]. The significant amount of heat required for the
45 regeneration of the solvent constitutes one of the main costs of any CO₂ capture process [6]. Thus, reducing
46 the energy consumption of CO₂ capture is a major motivation for the development of alternative processes.

47 One potential method to intensify CO₂ capture is the use of membrane gas-liquid contactors, in which CO₂
48 is absorbed into the liquid absorbent via mass transfer through a porous, non-selective membrane [7, 8].
49 Compared to conventional absorption equipment, membrane contactors offer a significant increase in the
50 interfacial area per unit volume [9, 10]. In addition, the interfacial area remains constant regardless of the
51 operating conditions, allowing flexible operation and independent adjustment of the gas and liquid flow
52 rates. The orientation of the module can also be freely selected, and its modular design allows for simple
53 and linear scale-up by increasing the number of modules and total membrane area.

54 To maximize the interfacial area, membrane gas-liquid contactors are commonly fabricated using hollow
55 fibers [7]. In hollow fiber modules, the membrane fibers are usually packed in parallel bundles inside a shell,
56 with one fluid flowing inside the fibers (lumen-side) and the other outside the fibers (shell-side). However,
57 the added mass transfer resistance caused by the membrane represents a disadvantage. In order to
58 minimize this resistance, microporous polymeric membranes are commonly utilized, with polypropylene
59 (PP) and polytetrafluoroethylene (PTFE) being particularly well studied [8]. The porous membranes are not
60 selective to CO₂; instead, selectivity is facilitated by the chemical absorption of CO₂ into the absorbent
61 solution. The membrane must be hydrophobic in order to resist wetting by the aqueous solution, as the
62 mass transfer is severely limited when the membrane is operated in wetted mode [11]. Selection of the
63 absorbent is also vital in preventing wetting. PP membranes have been found to be incompatible with
64 common amine absorbents for longer contact times due to the low surface tension of the liquid and the
65 chemical changes induced in the membrane surface structure [12, 13, 14].

66 Due to the wetting of PP membranes, which are more affordable than PTFE membranes, by aqueous
67 amines, the use of alternative absorbents in membrane contactors is of interest. The use of aqueous amino

68 acid salts has been proposed, as their CO₂ absorption rates and capacities are comparable to those of
69 amine solutions [15] and their high surface tension results in low wetting tendency [16]. In addition, the low
70 volatility and toxicity of amino acid salts compared to amines is advantageous. A variety of amino acid salts
71 have been considered for CO₂ absorption [17, 18]. One example is potassium glycinate [15, 19, 20, 21],
72 which is formed via the neutralization of the amino acid glycine with potassium hydroxide.

73 The application of a vacuum to lower the solvent regeneration temperature and the corresponding energy
74 consumption has been suggested [22, 23, 24, 25]. Lowering the regeneration temperature would also allow
75 common membrane materials incapable of withstanding high operating temperatures to be utilized. The
76 aim of the present study is to test and analyze the continuous absorption and desorption of CO₂ by a
77 membrane contactor with potassium glycinate as the absorbent. Reports of such continuous processes are
78 relatively scarce, as the majority of the previous literature has focused only on the absorption stage in non-
79 steady-state operation. However, some reports of continuous processes at the laboratory and pilot scale
80 are available [26, 27, 28, 29, 20].

81 Building on these developments, the present work demonstrates a continuously operated CO₂ capture unit
82 based on absorption in a membrane contactor and low-temperature desorption under an applied vacuum.
83 Here, the amino acid salt potassium glycinate is used as the absorbent, and a commercially available PP
84 hollow fiber module is used as the membrane contactor. The aim of the present paper is to provide an
85 overview of the equipment design, including its measurement and control capabilities, and to present and
86 discuss the initial observations and results obtained using the unit. A more detailed characterization of the
87 CO₂ absorption performance will be the subject of upcoming research.

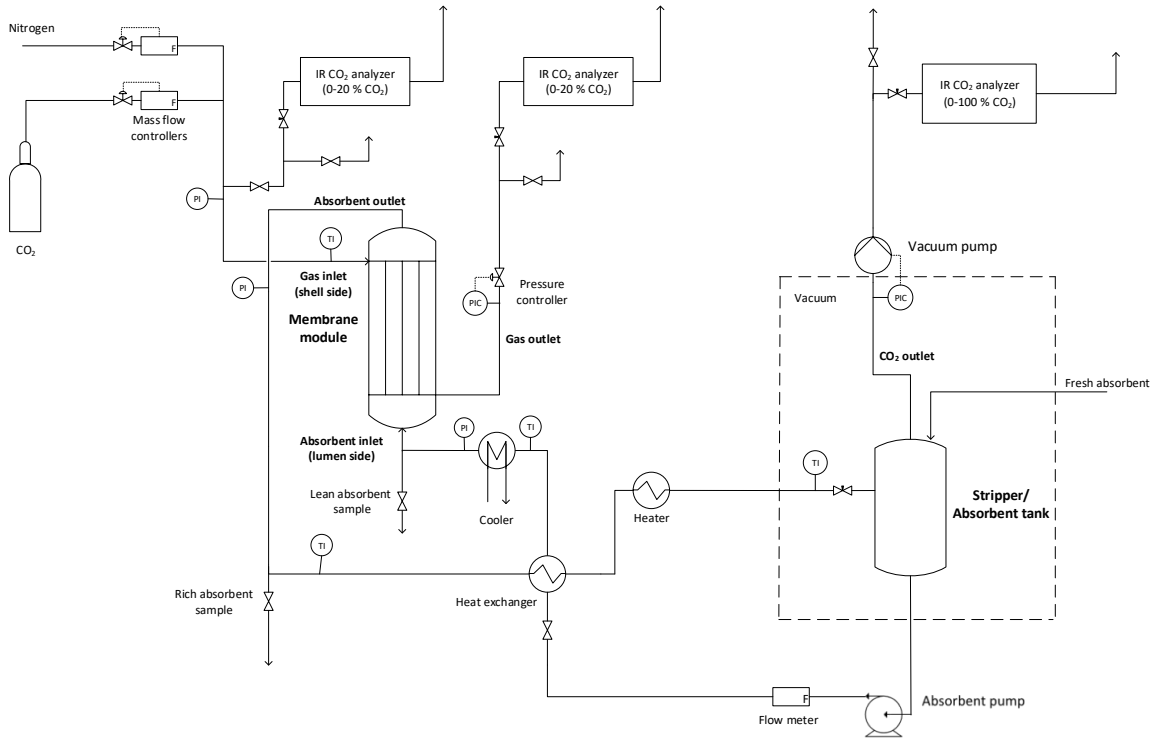
88 **2. Experimental**

89 **2.1. CO₂ capture unit**

90 The continuously operated CO₂ capture unit consists of a hollow fiber membrane module as the absorber,
91 a glass vessel that acts as a stripper, and a buffer tank for the absorbent solution. A flowsheet of the unit is
92 presented in Figure 1. The PP hollow fiber membrane contactor (Liqui-Cel 2.5 x 8 Extra-Flow) was supplied
93 by 3M. The membrane surface area of the module is 1.4 m². In the membrane module, the absorbent flows
94 upwards inside the hollow fibers (lumen side, volume 0.15 l), while the inlet gas flows countercurrent on the
95 shell side (volume 0.4 l). The inlet gas consists of a mixture of nitrogen (90% v/v, unless otherwise stated)
96 and CO₂ (10% v/v) for simulated flue gas composition. The gas flows are controlled by mass flow controllers
97 (Bronkhorst EL-FLOW Select, accuracy ±0.5% reading, ±0.1% full scale). The CO₂ concentration of the
98 inlet gas is verified using an IR analyzer (GMP251 probe, ±0.2 % CO₂, and Indigo 201 transmitter, both
99 supplied by Vaisala). The gas pressure is controlled using a back-pressure controller (Bronkhorst EL-
100 PRESS, ±0.1% reading, ±0.5% full scale) located at the membrane gas outlet. The pressure at the gas
101 outlet is maintained 0.1 bar below the liquid inlet pressure in order to avoid wetting of the membrane by the

102 absorbent solution. The CO₂ concentration of the outlet gas is measured using a separate IR analyzer
 103 (Vaisala GMP251 probe and Indigo 201 transmitter).

104



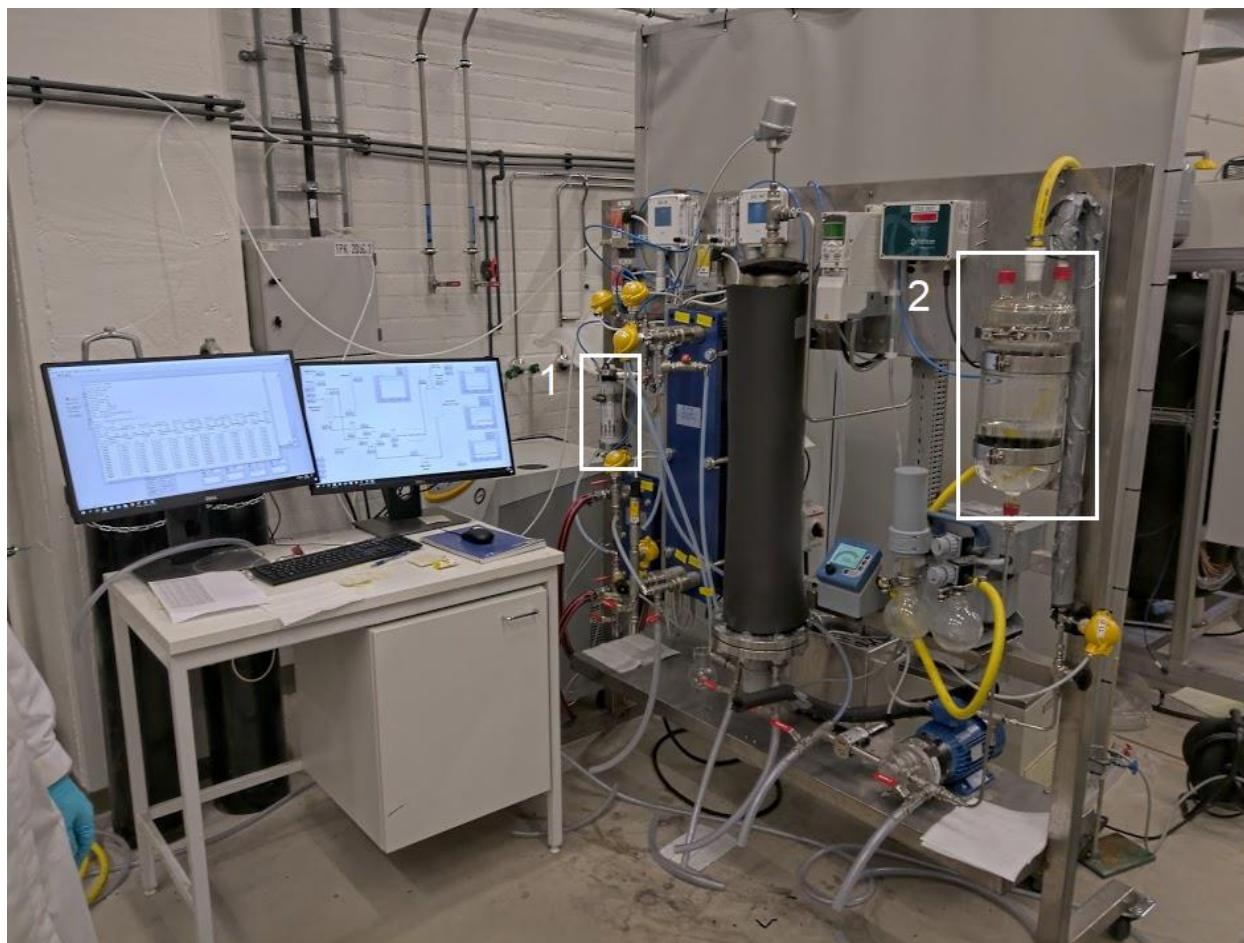
105

106 **Figure 1** Flowsheet of the experimental CO₂ capture unit.

107 Liquid is pumped through the system by a magnetic drive gear pump (Pulsafeeder Eclipse E12). The liquid
 108 flow rate is measured using a flow meter (Litre Meter LMX.48, $\pm 2\%$ reading) located directly after the pump.
 109 The CO₂-lean absorbent pumped at the regeneration temperature (60-80 °C) is first cooled in a plate heat
 110 exchanger (Alfa Laval, heat transfer area 1.6 m²) in which the heat is transferred to the cold absorbent
 111 exiting the membrane module. The liquid is then cooled to the absorption temperature (10-30 °C) in another
 112 plate heat exchanger (Alfa Laval, heat transfer area 0.2 m²) with cooling water as the cold fluid. The
 113 temperature of the cooling water is controlled via a circulating cooler (Lauda Variocool VC5000, ± 0.05 °C).
 114 After flowing through the membrane module, the CO₂-rich absorbent is first heated in the heat exchanger
 115 and then heated to the regeneration temperature in a hot water heater. The heater consists of an electronic
 116 heating element and a coiled absorbent pipe inside a stainless-steel shell. The liquid pressure on the
 117 absorption side can be adjusted via a manual needle valve located before the stripper.

118 In the vacuum regeneration experiments, the gas outlet from the stripper vessel was connected to a vacuum
 119 pump (Vacuubrand MZ 2C NT) via an automatic vacuum control unit (Vacuubrand CVC-3000, ± 1 mbar,
 120 hysteresis 2%). The vacuum pump is equipped with a condenser to condense the solvent and water vapor.

121 The outlet gas from the vacuum pump is routed to an IR CO₂-analyzer (CO2Meter CM-0052, $\pm 3\%$ reading,
122 $\pm 0.5\%$ full scale) with a 0-100% v/v measuring range. In addition to CO₂, the analyzer measures the oxygen
123 concentration with a 0-100 % v/v measuring range. **Figure 2** presents a photograph of the unit.



124
125 **Figure 2** Photograph of the CO₂ capture unit. 1. Membrane contactor, 2. vacuum desorption vessel.

126 2.2. Measurement and control

127 The control and data acquisition system is implemented using LabVIEW software. The data acquisition
128 system (NI cDAQ-9189) is used for data gathering and analog control signal output. 4-20 mA analog input
129 signals, measured with a NI 9208 module (accuracy $\pm 0.76\%$ reading), are used for temperature
130 measurements with Pt100 thermistors, pressure measurements, absorbent flow rate measurement, CO₂
131 analyzers, and mass flow controller feedback signals. A 4-20 mA analog output module (NI 9266, ± 0.76
132 reading, $\pm 1.4\%$ full scale) is used to set the reference values for the mass flow controllers, the back-
133 pressure controller, and the hot water heater. The internal temperature of the hot water heater is controlled
134 via a PI control implemented in LabVIEW, and the 4-20 mA reference signal, which is equal to a power of
135 0-4.5 kW, is supplied to the REVO S three-phase thyristor power controller.

136 The analog input signals are sampled with a frequency of 2 kHz, and the mean value of 200 samples is
137 then processed. Therefore, the control and data logging loop is executed with a frequency of 10 Hz. The
138 circulating cooler and the vacuum pump are controlled over an RS232 serial bus with a loop time of around
139 1 s. The absorbent pump frequency converter is controlled and the electrical power measurement is read
140 via Modbus/TCP with a loop time of roughly 1 s.

141 The electrical supply power is measured with a Sentron PAC3200 ($\pm 0.5\%$ reading) three-phase power
142 analyzer equipped with MAK 62/W 25/1A current transformers. The circulating cooler and hot water heater
143 are excluded from the electrical power measurement. Thus, the heating power of the absorbent is estimated
144 based on the measured flow rate and temperature difference.

145 **2.3. Procedure**

146 The potassium glycinate absorbent was prepared by the neutralization of glycine (Sigma-Aldrich, >99%)
147 with an equimolar amount of potassium hydroxide (Sigma-Aldrich, >85 wt%) in purified water. The solutions
148 were prepared in a glass vessel equipped with a cooling water jacket. The concentrations of all the solutions
149 were verified using potentiometric titration (Mettler-Toledo T50) using 1 M hydrochloric acid, and were within
150 1% of the nominal concentration. In the CO₂ capture experiments, the feed gas consisted of a mixture of
151 nitrogen (>99.5%) and CO₂ (>99.99%).

152 The equipment was filled with 6 l of the absorbent solution; using this volume, the liquid level in the
153 absorbent vessel was approximately half the vessel height. The system was started by flowing nitrogen
154 through the membrane contactor, after which the liquid flow was started. The flows of CO₂ and nitrogen
155 were then adjusted to reach the desired gas flow rate and composition. The CO₂ concentration (vol%) of
156 the feed gas was verified by directing a portion of the flow to the IR-analyzer. Following this verification, the
157 flow of feed gas to the analyzer was closed in order to measure the exact flow rate being delivered to the
158 membrane contactor. The heater and cooler (Lauda) were turned on to adjust the liquid temperature during
159 absorption and desorption. The pressure of the liquid entering the membrane module was adjusted using
160 the manual needle valve located before the desorption vessel. In the vacuum desorption runs, the vacuum
161 pump was switched on and the vacuum pressure was controlled by the vacuum control valve.

162 Unless otherwise stated, all experimental data were collected under steady-state conditions, as indicated
163 by stable operating conditions (temperatures, flow rates, and pressures) together with a stable CO₂
164 concentration at the outlet of the membrane module (measured using the IR analyzer). The steady-state
165 data were collected for periods of approximately 1 min in the LabView environment, and the final results
166 were calculated as the average values during the sampling period. Liquid samples were also collected
167 under steady-state conditions to analyze the CO₂ loading of the absorbent (mol CO₂ absorbed per mol of
168 potassium glycinate). One rich solvent sample (collected after the membrane module) and one lean solvent
169 sample (collected before the membrane module) were collected, and each sample was analyzed three
170 times by titration with 1 M hydrochloric acid and measuring the volume of the released CO₂. This analysis

171 was performed using a specifically designed Chittick-apparatus (Soham Scientific). The repeatability of the
 172 triplicate measurements was generally within 1.5% (relative standard deviation) with a maximum accepted
 173 deviation of 3.0%.

174 **2.4. Calculation of the results**

175 The CO₂ capture efficiency, i.e., the fraction of CO₂ absorbed from the feed gas, was calculated using the
 176 expression:

$$177 \quad \eta = \frac{\dot{n}_{\text{CO}_2,\text{in}} - \dot{n}_{\text{CO}_2,\text{out}}}{\dot{n}_{\text{CO}_2,\text{in}}} \cdot 100 \% \quad (1)$$

178 Where η is the capture efficiency (%) and $\dot{n}_{\text{CO}_2,\text{in}}$ and $\dot{n}_{\text{CO}_2,\text{out}}$ are the molar flows of CO₂ (mol s⁻¹) in the inlet
 179 and outlet gas, respectively. The CO₂ molar flux from the gas phase to the liquid phase in the membrane
 180 contactor was calculated as:

$$181 \quad N = \frac{\dot{n}_{\text{CO}_2,\text{in}} - \dot{n}_{\text{CO}_2,\text{out}}}{A} \quad (2)$$

182 Where N is the flux (mol m⁻² s⁻¹) and A is the membrane surface area (m²) of the module, as specified by
 183 the supplier.

184 The overall mass transfer process in a membrane gas-liquid contactor consists of diffusion of CO₂ from the
 185 bulk gas phase to the gas-membrane interface, through the membrane pores to the membrane-liquid
 186 interface, and to the bulk liquid followed by chemical and/or physical absorption. The process can be
 187 described by the resistance-in-series model using the individual mass transfer coefficients for the gas,
 188 liquid, and membrane phases. The overall gas-phase mass transfer coefficient is given by the following
 189 expression [30]:

$$190 \quad \frac{1}{K_g} = \frac{1}{k_g} + \frac{1}{k_m} + \frac{1}{mk_1E} \quad (3)$$

191 Where k_g , k_m , and k_1 are the gas, membrane, and liquid mass transfer coefficients, respectively, m is the
 192 distribution coefficient of CO₂ between the gas and liquid phases (Henry's constant in the case of physical
 193 absorption), and E is the enhancement factor caused by the chemical reaction, which is defined as the ratio
 194 of the absorption flux in the presence of the reaction and the flux with only physical absorption taking place.

195 To characterize the mass transfer performance of the present system, the gas-side overall mass transfer
 196 coefficient was calculated as:

$$197 \quad K = \frac{N}{\Delta C_m} \quad (4)$$

198 Where K is the overall mass transfer coefficient (m s⁻¹) and ΔC_m is the logarithmic mean driving force based
 199 on the gas-phase concentrations:

200
$$\Delta C_m = \frac{(C_{g,in} - C_{g,in}^*) - (C_{g,out} - C_{g,out}^*)}{\ln[(C_{g,in} - C_{g,in}^*) / (C_{g,out} - C_{g,out}^*)]} \quad (5)$$

201 Here, $C_{g,in}$ and $C_{g,out}$ are the measured CO₂ concentrations in the inlet and outlet gas (mol m⁻³) and
 202 $C_{g,in}^*$ and $C_{g,out}^*$ are the inlet and outlet gas-phase CO₂ concentrations (mol m⁻³) in equilibrium with the
 203 corresponding liquid-phase concentrations. The solubility data of Portugal et al. [31] for CO₂ in 1 M
 204 potassium glycinate were utilized to calculate the equilibrium concentrations. The gas-phase concentration
 205 was plotted against the liquid-phase concentration in the CO₂ partial pressure range relevant to the present
 206 experiments (100-1000 kPa), and an exponential curve was fitted to the data. As a result, the following
 207 correlation was found:

208
$$C_{g,i}^* = 1.4 \cdot 10^{-4} e^{0.014 C_{l,i}} \quad (6)$$

209 Where $C_{l,i}$ is the liquid-phase CO₂ concentration (mol m⁻³).

210 The heat duty required for heating the absorbent from the absorption temperature to the desorption
 211 temperature was estimated as:

212
$$Q_h = \rho \dot{V} c_p \Delta T \quad (7)$$

213 Where Q_h is the heat duty (W), \dot{V} is the absorbent volume flow rate (m³ s⁻¹), ΔT is the temperature difference
 214 (°C) between the desorption temperature and the temperature of the pre-heated absorbent leaving the plate
 215 heat exchanger, ρ is the absorbent density, approximated by the density of water (1000 kg m⁻³), and c_p is
 216 the absorbent heat capacity, which was approximated using the heat capacity of pure water (4186 J kg⁻¹ K⁻¹).
 217 1).

218 The specific heat consumption (J mol⁻¹) per mol of CO₂ captured was then calculated as:

219
$$e_{h,CO_2} = \frac{Q_h}{NA} \quad (8)$$

220 The specific electricity consumption (J mol⁻¹) was similarly calculated as:

221
$$e_{e,CO_2} = \frac{Q_e}{NA} \quad (9)$$

222 Where Q_e is the total measured electrical power (W) of the absorbent pump and the vacuum pump.

223 2.5. Initial observations and challenges

224 Based on the initial experimental runs discussed here, it is apparent that the CO₂ absorption stage utilizing
 225 a membrane contactor can be run continuously with high degree of stability, providing consistent and
 226 reliable measurement data. The automatic gas-side pressure control is capable of maintaining the
 227 appropriate trans-membrane pressure under the dynamic conditions present during the start-up phase of
 228 the capture unit. The temperature of the absorbent solution entering the membrane module is effectively

229 controlled by the heat exchanger and thermostat. Based on the limited operational time thus far, the PP
230 membrane module appears to be compatible with the amino acid salt solution, and no indication of
231 membrane wetting has been observed. At the start of the experiments, with unloaded absorbent, the mass
232 transfer performance of the membrane contactor is excellent, with nearly 100% of the CO₂ being absorbed
233 (Section 3).

234 However, from the initial results discussed below, it is clear that the overall CO₂ capture rate under steady-
235 state conditions is limited by the performance of the current simple desorption unit. The glass vessel utilized
236 as the desorber does not feature a distributor for the incoming absorbent and contains no packing to
237 increase the gas/liquid contact area. As a result, the flow pattern of the liquid entering the vessel is not
238 optimal, and the interfacial area is limited.

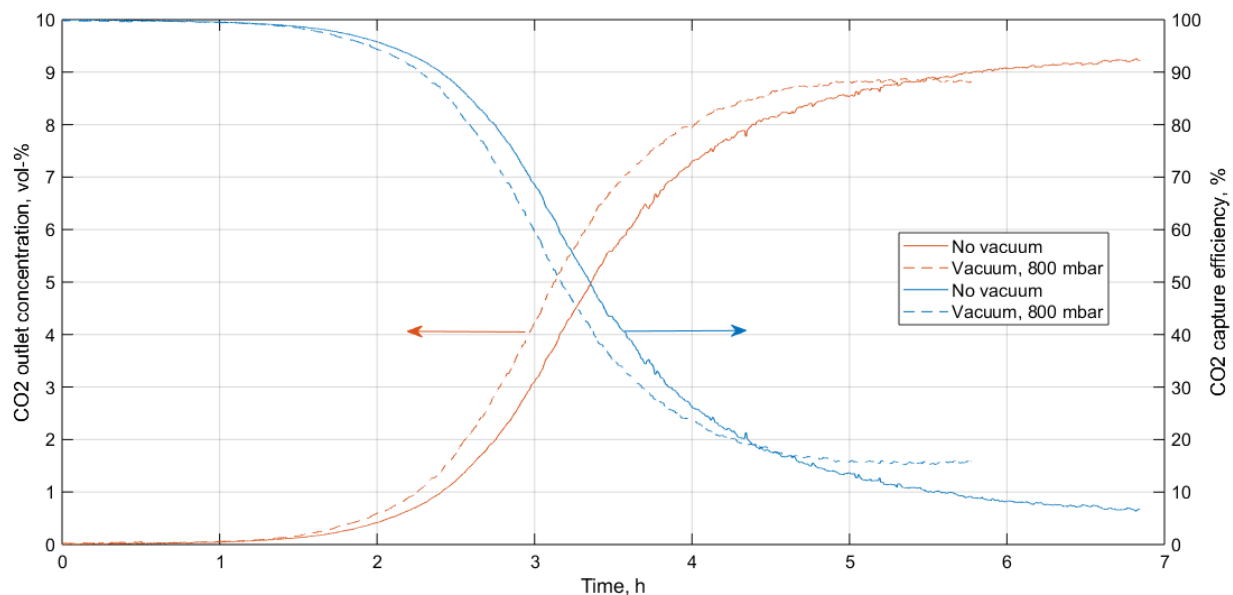
239 The desorption temperature is limited by the use of water as the heating medium in the absorbent heater.
240 The temperature is limited to an absolute maximum of 80 °C, and even at that temperature, stable operation
241 during longer periods was periodically disrupted by the overheating of the water bath. Higher temperatures
242 could be achieved by using a different heat transfer fluid. However, operating the desorber at relatively low
243 temperatures is preferred due to potential energy savings and to allow the utilization of low-grade heat or
244 heat pumps, increased absorbent stability, and the possibility of utilizing membrane contactors at the
245 desorption stage. The latter could significantly improve the mass transfer of CO₂ from the solution by
246 increasing the interfacial area.

247 The rate at which water evaporated from the absorbent depended on the desorption temperature and
248 vacuum pressure, and the vapor escaping the desorption vessel accumulated in the cold trap of the vacuum
249 pump. In order to avoid excessive evaporation of water, the vacuum pressure was limited based on the
250 boiling point of water at the desorption temperature. Operation at boiling conditions might have improved
251 the desorption performance in the experiments due to the increased interfacial area created by the vapor
252 bubbles and the sweeping effect of the vapor, resulting in a decreased partial pressure of CO₂ inside the
253 vessel. Ideally, the condenser should be placed directly on top of the desorption vessel to allow the reflux
254 of water.

255 **3. Results and discussion**

256 This section presents a summary of the preliminary results from the initial runs using the CO₂ capture unit.
257 Figure 3 presents an example of the evolution of the CO₂ concentration at the membrane outlet during start-
258 up. In addition to the concentration, the corresponding CO₂ capture efficiency is also presented in the figure,
259 and the profiles obtained using no vacuum and an 800-mbar vacuum at a desorption temperature of 60 °C
260 are shown. During the first hour of operation, the unloaded absorbent was capable of near-complete
261 absorption of the CO₂ fed to the membrane module, with a capture efficiency of approximately 100%.
262 However, as the absorbed CO₂ was not completely desorbed from the solution, the CO₂ loading continually
263 increased. The increased loading gradually led to a decrease in the CO₂ flux from the feed gas to the

264 absorbent, and an increasing fraction of the CO₂ in the feed gas passed through the membrane module
 265 uncaptured. The steady state was reached when the absorption flux became equal to the flux of CO₂
 266 desorbed from the solution.



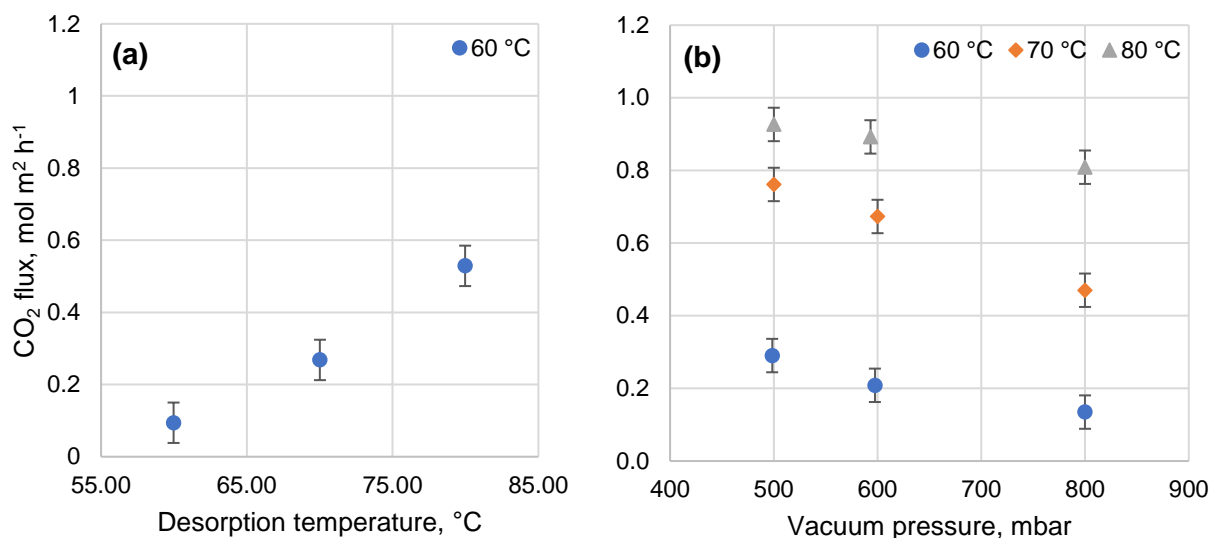
267
 268 **Figure 3** CO₂ concentration and CO₂ capture efficiency during start-up: liquid: 1 l/min (3 M PG), gas:
 269 5 l/min (10% CO₂), absorption: 20 °C, desorption: 60 °C.

270 When vacuum-assisted desorption was used, the steady state was achieved sooner, and the steady-state
 271 CO₂ concentration at the outlet was slightly lower (higher capture efficiency) compared to in desorption
 272 without vacuum. This indicates that the vacuum increased the CO₂ flux in the desorption stage. However,
 273 even using an 800-mbar vacuum, the desorption rate clearly limited the steady-state absorption
 274 performance, with the steady-state CO₂ capture efficiency of approximately 16%, compared to
 275 approximately 7% without the vacuum.

276 Figure 4a presents the effect of the desorption temperature on the CO₂ flux for desorption without vacuum.
 277 Clearly, increasing the temperature had a favorable effect on the absorption performance. This can be
 278 explained by the more effective desorption of CO₂ from the loaded solution, leading to a lower CO₂ loading
 279 in the lean absorbent and increased driving force for absorption. The desorption temperature affects the
 280 solubility and resulting equilibrium CO₂ loading of the absorbent, the kinetics of the reactions involved in
 281 desorption, and the mass transfer of the desorbed CO₂. However, a detailed discussion of these effects is
 282 outside the scope of the present report. In summary, the overall effect of the desorption temperature was
 283 drastic in the studied temperature range, with the absorption flux increasing by 460% when the temperature
 284 was increased from 60 °C to 80 °C.

285

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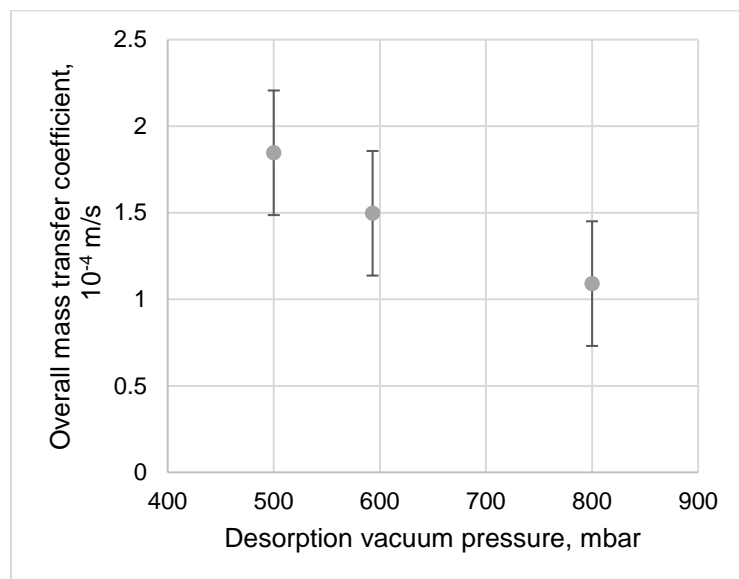


287 **Figure 4** (a) Dependence of the CO₂ absorption flux on the desorption temperature (no vacuum).
 288 (b) Dependence of CO₂ absorption flux on the vacuum pressure at desorption
 289 temperatures of 60, 70, and 80 °C. Absorbent flow rate: 1 l/min (1 M potassium glycinate),
 290 feed gas flow rate: 5 l/min (10 % CO₂), absorption temperature: 20 °C. Error bars
 291 correspond to the 95% confidence interval as determined from repeat experiments.

292 Figure 4b presents the CO₂ flux during desorption under a 800 to 500 mbar vacuum at 60-80 °C. Compared
 293 to the non-vacuum results in Figure 4a, the flux generally increased, and decreasing the pressure led to
 294 improved performance. The favorable effect of the vacuum can likely be explained by the decreased CO₂
 295 partial pressure in the gas/vapor of the desorption vessel, leading to an increased driving force for
 296 desorption. In addition, the vacuum pump continuously swept the desorbed CO₂ out of the vessel, which
 297 also increased the driving force. However, the effect of temperature was more pronounced than that of the
 298 vacuum pressure. For example, at 60 °C, the flux increased by 115% when the vacuum pressure was
 299 lowered from 800 mbar to 500 mbar, while increasing the temperature from 60 °C to 80 °C at 800 mbar of
 300 vacuum resulted in a 500% increase in the flux.

301 Figure 5 presents the overall mass transfer coefficients calculated from Eq. (3) for the different desorption
 302 pressures at a temperature of 80 °C. The overall mass transfer coefficient was found to increase with
 303 decreasing desorption pressure. This trend was consistent with the variation in the CO₂ flux (Figure 4b)
 304 with vacuum pressure, and can be explained by the increased desorption efficiency and the resulting

305 decrease in the CO₂ loading of the lean absorbent entering the membrane contactor. The lean adsorbent
 306 loading varied from 0.48 mol mol⁻¹ at 800 mbar to 0.42 mol mol⁻¹ at 500 mbar.



307
 308 **Figure 5** Variation in the gas-side overall mass transfer coefficient with the desorption vacuum
 309 pressure at a desorption temperature of 80 °C. Absorbent flow rate: 1 l/min (1 M potassium
 310 glycinate), feed gas flow rate: 5 l/min (10 % CO₂), absorption temperature: 20 °C. Error
 311 bars correspond to the 95% confidence interval as determined from repeat experiments.

312 As the driving force for the physical mass transfer from the gas to the liquid was included in the calculation
 313 of the overall mass transfer coefficient, the variation in the mass transfer coefficient likely corresponded to
 314 variation in the rate of chemical absorption. The higher lean loading under the less-favorable desorption
 315 conditions would result in a lower concentration of free amino acid salt in the solution, and a correspondingly
 316 lower reaction rate [16]. A similar explanation was given by Lu et al. [32], who also presented data on the
 317 overall mass transfer coefficient as a function of the lean solvent loading using N-methyldiethanolamine as
 318 the absorbent. Variation in the absorption flux with the CO₂ loading of the lean solution was also reported
 319 for various amino acid salt solutions in a screening study by He et al. [33].

320 The highest overall mass transfer coefficient was $1.9 \times 10^{-4} \text{ m s}^{-1}$. Table I provides a comparison of this
 321 value to those in previous reports in the literature; all the listed references employed polypropylene hollow
 322 fiber membrane contactors with various absorbents. It should be noted that direct comparison of values
 323 determined under very different operating conditions, including different gas and liquid flow rates,
 324 temperatures, and solvent type and loadings, should be performed with caution. However, the value found
 325 here is well within the range of values found in the literature. Using amino acid salt solutions, Feron and
 326 Jansen [26] reported a value one order of magnitude higher utilizing a proprietary solution and custom-built
 327 transversal flow membrane module. Lu et al. [21] obtained a value very similar to our result using a
 328 potassium glycinate solution. While most of the data were collected using fresh, unloaded solvent, some

329 authors also have also presented results for CO₂-loaded solutions. Compared to these types of results [28,
 330 32, 34] the performance of the present system is fairly competitive, especially considering its relatively high
 331 lean loading of 0.40 mol mol⁻¹.

332

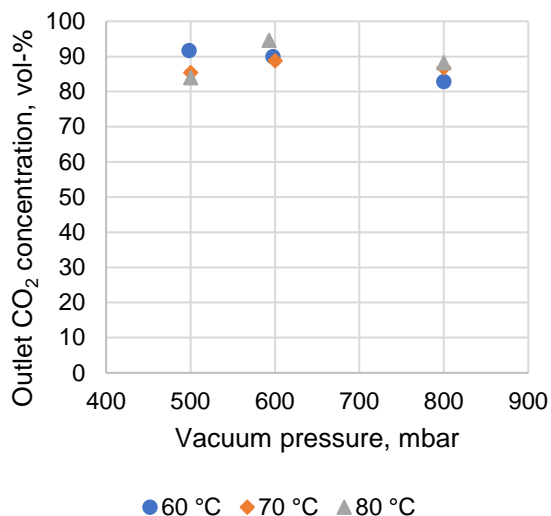
333 **Table I** Comparison of experimental overall mass transfer coefficients in CO₂ absorption using
 334 polypropylene membrane contactors and various absorbents.

Reference	Absorbent	Overall mass transfer coefficient, m s ⁻¹	Notes
This work	Potassium glycinate	1.9×10^{-4}	Continuous absorption-desorption, lean loading 0.42
Feron and Jansen, 2002 [26]	CORAL (Proprietary amino acid salt based)	1.6×10^{-3}	Transversal flow module
Mavroudi et al., 2003 [35]	DEA	3.5×10^{-4}	Liqui-Cel module similar to this work
Dindore et al., 2004 [36]	Propylene carbonate	2.0×10^{-5}	Physical absorbent
Kosaraju et al., 2005 [28]	Polyamidoamine dendrimer	2.15×10^{-5}	Continuous absorption-stripping, lean loading not specified
Lu et al., 2005 [32]	MDEA	3.0×10^{-5} 0.8×10^{-5} (lean loading 0.3)	Variation of overall mass transfer coefficient with lean loading presented
Franco et al., 2008 [34]	MEA	4.3×10^{-4}	Simulated regenerated solution with lean loading of 0.27-0.30
Lu et al., 2009 [21]	Potassium glycinate	1.7×10^{-4}	

Lin et al., 2009 [37]	MDEA, AMP	3.3×10^{-4} (AMP) 7.7×10^{-5} (MDEA)	
Chabanon et al., 2011 [12]	MEA	3.3×10^{-4}	Wetting and performance monitored over long operating periods
Wang et al., 2013 [38]	Blended MEA, MDEA	6.8×10^{-4}	
Scholes et al., 2015 [39]	MEA	5.5×10^{-6}	Significant pore wetting observed
Scholes et al., 2015 [40]	BASF PuraTreat (Proprietary amino acid salt based)	7.0×10^{-6}	Pilot plant with real flue gas, significant pore wetting due to pressure fluctuations

335

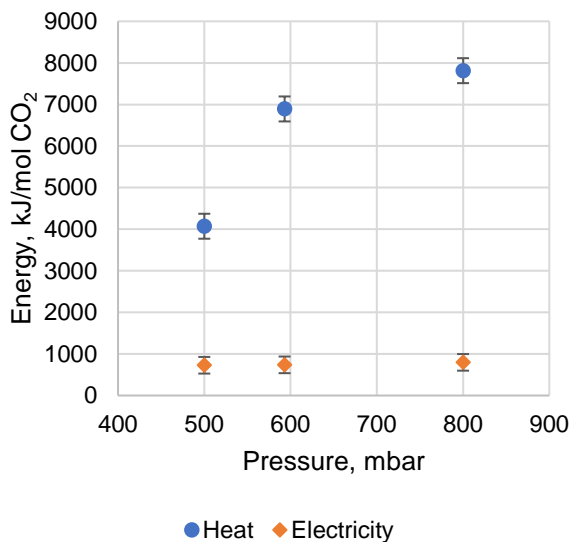
336 The measurement of the CO₂ concentration of the outlet gas leaving the desorption unit allowed evaluation
337 of the selectivity of the absorption process. As the feed gas in the present experiments consisted of only
338 CO₂ and nitrogen, the analysis gave an indication of the CO₂/N₂ selectivity, as dictated by the chemical
339 nature of the absorbent solution. Figure 6 presents the CO₂ concentration of the outlet gas during vacuum
340 desorption at 500-600 mbar and 60-80 °C. The CO₂ concentration ranged from 84 to 95 vol%, and no trends
341 could be observed with respect to the desorption temperature and vacuum pressure. These values
342 corresponded to CO₂/N₂ selectivities of 5 to 20. However, the reliability of these measurements was
343 questionable, as oxygen concentrations of up to 3 vol% were also detected in the outlet gas. As oxygen
344 was not present in the feed gas, the presence of oxygen can only be explained by air remaining in the
345 system or by leaks in the vacuum system. As such, the measured CO₂ concentrations should be considered
346 only as rough estimates, probably giving the lower limit of the actual concentration range.



347

348 **Figure 6** Effect of vacuum pressure and desorption temperature on the CO₂ concentration of the
 349 outlet gas leaving the desorber. Absorbent flow rate: 1 l/min (1 M potassium glycinate),
 350 feed gas flow rate: 5 l/min (10 % CO₂), absorption temperature: 20 °C.

351 The energy consumption of the capture unit consists of the heat required to heat the loaded absorbent to
 352 the desorption temperature and the electricity consumed by the absorbent and vacuum pumps. Figure 7
 353 presents the specific energy consumption obtained at a desorption temperature of 80 °C under 500-800
 354 mbar vacuum. The electricity consumption was minor compared to the heat required: 4.1 MJ/mol of heat
 355 and 0.7 MJ/mol of electricity were consumed during desorption at 500 mbar. These conditions represented
 356 the lowest energy consumption among the preliminary runs, as the specific energy consumption was higher
 357 when lower desorption temperatures were used. The increased heating requirement at higher temperature
 358 was offset by the increased desorption efficiency. For the same reason, lowering the vacuum pressure led
 359 to lower heat consumption, while the specific electricity consumption remained essentially constant due to
 360 the increased power required by the vacuum pump.



361
 362 **Figure 7** Specific heat and electricity consumption per mole of CO₂ captured during desorption at
 363 80 °C and 500-800 mbar vacuum. Absorbent flow rate: 1 l/min (1 M potassium glycinate),
 364 feed gas flow rate: 5 l/min (10% CO₂), absorption temperature: 20 °C.

365 The data available in the literature for the energy consumption of regeneration using membrane and/or
 366 vacuum technology are relatively limited, and the results vary significantly depending on the type of
 367 experimental system employed and the method used to estimate the energy consumption. Table II presents
 368 a summary of the specific energy consumption values found in the literature. Two types of approaches can
 369 be identified in the referenced works. In the first approach, the experiments and calculations are limited to
 370 the stripping stage in various configurations, and absorption and solvent circulation are not included [41,
 371 42, 43]. Here, the energy consumption values range from 200 to 780 kJ kg CO₂⁻¹.

372 In the approach followed in this work, similar to Mulukutka et al. [44], the heat consumption is estimated
 373 based on the heating of the solvent in continuous absorption-stripping circulation. The energy consumption
 374 found in the current study is closely comparable to that reported by Mulukutka et al. This method seems to
 375 lead to energy consumption figures that are at least two orders of magnitude higher than those obtained
 376 using the first method. Part of the difference seems to arise from the experimental configuration: limiting
 377 the experiments to only the stripping stage allows the optimization of the operating conditions for effective
 378 and energy efficient desorption, while the operation in the continuous absorption-stripping mode requires
 379 also the consideration of the absorption performance when setting the operating parameters, such as the
 380 liquid flow rate. Compared to the work of Wang et al. [43], the liquid flow rate is higher in our case, leading
 381 to higher sensible heat requirement for heating the solvent. However, the major difference is the much
 382 higher desorption efficiency of the membrane contactor stripping unit demonstrated by Wang et al. [43],
 383 indicating the potential for this type of technology.

384

385 **Table II** Comparison of the specific energy consumption in vacuum- and membrane-based CO₂
 386 stripping processes.

Reference	Method	Energy consumption, kJ kg CO ₂ ⁻¹	Notes
This work	Potassium glycinate, 60-80 °C, 50-80 kPa	1.05 × 10 ⁵ (heat) 1.82 × 10 ⁴ (electricity)	Includes solvent heating and pumping, vacuum pump
Yan et al., 2009 [41]	MEA, 35 °C, 10-50 kPa	200	Includes vacuum pump but not solvent pumping or heating
Fang et al., 2012 [42]	MEA, PP membrane contactor as stripper, steam sweep, 70 °C, 10-48 kPa	200	Energy consumption increased at lower vacuum due to increased steam generation Solvent pumping and heating not included
Wang et al., 2014 [43]	MEA, PP, and PVFD contactors, 75 °C, 5-80 kPa	780	Includes sensible and latent heat of solvent Higher desorption flux with PVDF but improved stability with PP contactor
Mulukutka et al., 2014 [44]	Ionic liquid absorbent, PP module with fluorosiloxane coating, continuous absorption (50 °C) and stripping (85 °C, 98 kPa)	1.36 × 10 ⁵	Considers heat of absorption and sensible heat of solvent, but not vacuum pump

387

388 The primary approach for improving the energy efficiency would be to increase the desorption efficiency.
 389 Increasing the temperature is not the preferred approach, as operation at relatively low regeneration
 390 temperatures is the explicit aim. However, applying lower vacuum pressures and employing intensified
 391 mass transfer equipment, including membrane contactors, is another potential approach. The use of
 392 membrane contactors in the desorption stage in conjunction with an applied vacuum to increase the driving
 393 force and gas sweep could significantly increase the desorption performance. It should be noted that
 394 membrane-based desorption is limited to lower regeneration temperatures due to the limited high-

395 temperature stability of polymeric membranes. Intensification of the desorption stage could also be
396 achieved by means of ultrasound radiation, which will also be explored in a future work.

397 In addition to modifications to the design of the experimental unit, the energy efficiency could also be
398 improved by optimizing the operating parameters, such as the liquid and gas flow rates and the absorbent
399 type and concentration. As the energy required for heating the solvent is linearly dependent on the liquid
400 flow rate, minimizing the liquid flow rate relative to the gas flow rate would yield significant efficiency
401 benefits. An optimum ratio could likely be found at which the liquid flow rate would be minimized without
402 significant reduction in the CO₂ flux. At the optimum liquid/gas flow ratio, absorption would still be controlled
403 by interphase mass transfer, while further decrease in the liquid flow rate would result the absorption being
404 limited by the chemical reaction due to the depletion of free amino acid salt [16]. Increasing the absorbent
405 concentration should also result in improved efficiency, as a greater concentration of CO₂ could be
406 adsorbed while circulating and heating the same amount of liquid in the system, and accordingly, the CO₂
407 desorption flux would be higher at the same solvent heating duty.

408 **4. Conclusion**

409 A continuously operated CO₂ capture unit based on absorption in a membrane contactor and low-
410 temperature desorption under an applied vacuum was demonstrated. The purpose of the unit is to capture
411 CO₂ from simulated flue gas and process CO₂ stream concentrations down to ambient concentration. The
412 experimental unit incorporates comprehensive measurements and a high level of automation, with heat
413 integration and continuous measurement of electricity consumption potentially providing realistic estimates
414 of the energy consumed in the capture process.

415 In preliminary runs using a potassium glycinate absorbent, the steady-state CO₂ absorption performance
416 was found to be limited by the desorption stage. During start-up, the unloaded absorbent could achieve
417 nearly complete absorption of the CO₂ fed to the membrane absorption module; the capture efficiency
418 subsequently decreased as the CO₂ loading of the absorbent increased. Higher desorption temperatures
419 and lower vacuum pressures were found to increase the desorption efficiency, resulting in a higher CO₂
420 absorption flux. The highest flux of 0.82 mol m⁻² h⁻¹ (corresponding to 36 g CO₂ captured per hour) was
421 found at a desorption temperature of 80 °C under a 500-mbar vacuum. The corresponding overall mass
422 transfer coefficient (1.9×10^{-4} m s⁻¹) was comparable to previously published values for polypropylene
423 contactors with various absorbents.

424 Increasing the desorption temperature and lowering the vacuum pressure also resulted in decreased
425 specific energy consumption, as the increased heat and electricity consumption were offset by the
426 increased desorption rate. The lowest specific heat and electricity consumption of 4.1 MJ/mol CO₂ (29.0
427 MWh/t) and 0.7 MJ/mol CO₂ (5.0 MWh/t) were achieved at 80 °C and 500 mbar vacuum. The observed
428 purity of the desorbed CO₂ ranged from 84 to 95 vol%; however, the accuracy of these measurements was
429 potentially compromised by the presence of air in the system.

430 Based on these initial findings, it is clear that the desorption efficiency of the unit must be improved via
 431 modification of the equipment setup and operational conditions. Optimization of the setup and conditions is
 432 facilitated by the modular nature of the unit, which allows it to operate with alternative membrane absorption
 433 modules and desorption configurations. The use of membrane contactors in the desorption stage could
 434 improve the performance via increased interfacial area. Lower vacuum pressures could be attained by
 435 eliminating the current operational limitations of the system. At present, the low desorption efficiency leads
 436 to very high values for the estimated specific energy consumption. In addition to improvements to the
 437 equipment setup, the specific energy consumption could be improved by optimization of the operating
 438 parameters, for example, by minimizing the liquid/gas flow ratio and increasing the absorbent concentration.

439 **Nomenclature**

440	A	membrane surface area, m^2
441	C	concentration, mol m^{-3}
442	C^*	equilibrium concentration, mol m^{-3}
443	c_p	heat capacity, $\text{J kg}^{-1} \text{K}^{-1}$
444	E	enhancement factor, -
445	e	specific energy, J mol^{-1}
446	K	gas-side overall mass transfer coefficient, m s^{-1}
447	k	individual mass transfer coefficient, m s^{-1}
448	N	molar CO_2 flux, $\text{mol m}^{-2} \text{s}^{-1}$
449	\dot{n}	molar flow rate, mol s^{-1}
450	Q	duty, W
451	T	temperature, K
452	\dot{V}	volumetric flow rate, $\text{m}^3 \text{s}^{-1}$
453	ΔC_m	logarithmic mean driving force, -
454	η	CO_2 capture efficiency, %
455	ρ	density, kg m^{-3}

456

457 Subscripts

458 e electricity
459 g gas
460 h heat
461 l liquid
462 in inlet to the membrane module
463 m membrane
464 out outlet from the membrane module

465

466 5. References

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